#### **Michele Allegra**



### **Overview**

#### The intrinsic dimension of a dataset



The case of variable ID



#### The TWO-NN approach for ID estimation



Application to a molecular dynamics trajectory



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Clustering by the local intrinsic dimension

### Intrinsic dimension

- Data are defined in a space with D variables
- However, the data lie on hypersurface of lower dimension d < D
- This dimension is called *intrinsic dimension*



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### Intrinsic dimension

The state of a molecule is described by 6N variables



Due to soft and hard constraints, the independent phase space directions are d << 6N

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### **ID** estimation

- Data are sampled from a distribution with density  $\rho(X)$
- If  $\rho(X)$  is onstant, distances between points in the dataset follow scaling laws that depend only on d
- Example: correlation dimension
  - If  $\rho(X)$  is constant, # of points at distance <  $\epsilon$  from point *i* scales as



- *d* can be estimated with simple linear fit
- when  $\rho(X)$  is variable, the scaling is violated, estimation fails dramatically

# ID estimation: TWO-NN

E Facco, M D'Errico, A Rodriguez, A Laio, Scientific Reports 7, 12140. (2017)

• TWO-NN: estimating the ID in case of (strongly) variable density

Make two **broad assumptions**:

- H1) the data points  $x_i$  are **independent samples** from a density  $\rho(x)$ .
- H2) local uniformity:  $\rho(x) \sim \text{const.}$  in the region containing the first 2 neighbors of  $x_i$
- $r_{i_1}, r_{i_2}$  distances of 1st and 2nd neighbor of point i
- $\mu_i = d_{i2}/d_{i1}$  follows a **Pareto distribution:**  $P(\mu) = d\mu^{-d}$
- The distribution of  $\mu$  depends only on d



# ID estimation: TWO-NN

- $r_{i_1}, r_{i_2}$  distances of 1st and 2nd neighbor of point i
- $\mu_i = d_{i2}/d_{i1}$  follows a **Pareto distribution:**  $P(\mu) = d\mu^{-d} \rightarrow F(\mu) = 1 \mu^{-d}$
- Fit the empirical cumulative distribution of the  $\mu_i$  and estimate d
- Equivalently, linear fit on  $log(1-F(\mu))=-d log\mu$



### The problem of multiple IDs

the data may lie on several manifolds, each with different ID



Simple example: just merge two datasets with different ID

#### Is this an artificial oddity or a common situation?

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- TWO-NN assumptions:
  - H1) the data points  $x_i$  are **independent samples** from a density  $\rho(x)$ .
  - H2) local uniformity:  $\rho(x) \sim \text{const.}$  in the region containing the first 2 neighbors of  $x_i$

#### Additional assumption:

• H3) the distribution  $\rho(x)$  has support on K manifolds with different IDs  $d=d_1,...,d_{\kappa}$ 

• Under H1), H2), H3) the distribution of  $\mu$  is simply a **mixture of Pareto distributions** 

$$\mathcal{L}(\boldsymbol{\mu}|\mathbf{d},\mathbf{p}) = \prod_{i=1}^{N} \sum_{k=1}^{K} p_k d_k \mu_i^{-d_k-1}$$

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Estimate parameters **p,d** with Bayesian approach

- Fix  $P_{prior}(\mathbf{d}, \mathbf{p})$
- Compute posterior distribution  $P_{post}(\mathbf{d}, \mathbf{p}) \propto \mathcal{L}(\boldsymbol{\mu} | \mathbf{d}, \mathbf{p}) P_{prior}(\mathbf{d}, \mathbf{p})$
- Average  $\mathbf{d}^e, \mathbf{p}^e = \langle \mathbf{d}, \mathbf{p} \rangle_{post}$
- to sample the posterior, we must introduce latent variables Z=Z<sub>1</sub>,...,Z<sub>κ</sub> manifold membership of each point

$$\mathcal{L}(\boldsymbol{\mu}|\mathbf{d}, \mathbf{p}, \mathbf{Z}) = \prod_{i=1}^{N} p_{Z_i} d_{Z_i} \mu_i^{-d_{Z_i}-1}$$

• Estimate jointly **d,p,Z** by Gibbs Sampling of the posterior distribution

#### Little problem: this approach does not work!

```
Two manifolds of dimension d_1=4 and d_2=5,...,9 (Gaussian \rho)
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```
estimation of d_1 and d_2 is inaccurate
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estimation of Z is completely wrong (mutual information MI between true and estimated membership Z is 0)



Let the neighborhood of point *i* be defined by its first *q* neighbors

- $n_i^{in}$  # neighbors with same Z as *i*
- $n_i^{out}$  # neighbors with different Z

We get non-uniform neighborhoods:  $n_i^{out} > n_i^{in}$ Problem in correctly estimating Z!

One more assumption:

H4) the manifolds have a small intersection:

neighborhoods must be approximately uniform

We enforce this through additional term in the likelihood



We enforce uniform neighborhoods through **additional term in the likelihood** 

$$\mathcal{L}(n^{in}|\mathbf{Z}) = \prod_{i} \frac{\zeta^{n_i^{in}} (1-\zeta)^{n_i^{ou}}}{\mathcal{Z}}$$

 $\zeta > \frac{1}{2}$  Probability that two neighbors are in the same manifold

Now we get uniform neighborhoods and correct estimates!





### Heterogeneous ID algorithm (Hidalgo) M Allegra, E Facco, A Laio and A Mira, arXiv:1902.10459 (2019)

#### Find regions (manifolds) of different ID in the data

Works also for nonlinear and topologically complex manifolds

E.g. circle in d=1, swiss roll in d=4, torus d=2, sphere d=5, sphere d=9



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### Heterogeneous ID algorithm (Hidalgo) M Allegra, E Facco, A Laio and A Mira, arXiv:1902.10459 (2019)

#### Find regions (manifolds) of different ID in the data

Works also for nonlinear and topologically complex manifolds Circle d=1, swiss roll in d=4, torus d=2, sphere d=5, sphere d=9 Estimated dimensions 0.9,2.0,4.1,5.2,8.5



### Real example: phase space of folding protein



- consider a simulation of unfolding/refolding villing headpiece
- for each of the N ~ 32,000 configurations, D=32 dihedral angles.

#### We find four manifolds,

- three with low dimensions d=11.8,d=12.9, d=13.2
- one with high dimension d=22.9

Which configurations are assigned to the different manifolds?

Consider q=fraction of native contacts (=degree of folding)

### Example: phase space of folding protein



- Folded configurations are in the high-dimensional manifolds
- The local ID is able to discriminate between folded and unfolded configurations

The effective # of phase space directions the system can explore varies in the two states

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### Example: brain imaging time series

- Consider 202 fMRI images of the brain during visuospatial task
- N=40,000 brain voxels; for each voxel, BOLD time series with D=202 points
- We find two manifolds with dimensions d=31.9, d=16.1
- Consider Φ, "clustering frequency", measuring how many times a voxels participates to transient coherent patterns



Companies with high  $\Phi$  involvement are preferentially assigned to the high dimensional manifolds

 $\boldsymbol{\Phi}$  is related to task involvement

### Conclusions

- We extended a recently developed ID estimator, TWO-NN, to the case where the ID is variable in a single dataset
- The method rests on quite weak assumptions (local uniformity of density and dimension)
- We find regions of different local ID in the data
- In real data, we find large variations of the ID, highlighting relevant structure in the data
- ID estimation is not just a preliminary step, but can highlight structure in the data

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# Aalto University

# Thank you for your attention!!

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#### What is the problem?

Pareto distributions with different *d* are highly overlapping!

The Z assigment in the Gibbs sampling, based on  $\mu$ , is not reliable



### ID estimation: projective approach

- Project *D*-dimensional data into lower dimension d:  $\Pi^d$ :  $\mathbf{x}_i \in \mathbb{R}^D \mapsto \mathbf{y}_i \in \mathbb{R}^d$
- Try different *d* and evaluate for each a "loss function"  $\mathcal{L}(\Pi^d)$
- $\mathcal{L}(\Pi^d)$  measures the "data loss" occurring in the projection.

 $\mathcal{L}(\Pi^d) = \sum_i ||\mathbf{x}_i - \mathbf{y}_i||^2 \quad \text{preservation of original distance relations}$  $\mathcal{L}(\Pi^d) = \sum_i \mathbf{x}_i \mathbf{x}_i^T - \mathbf{y}_i \mathbf{y}_i^T \quad \text{preservation of original covariance matrix}$ 

- d is "estimated" from tradeoff between dimension reduction and data loss
- Problem (1): Computationally burdensome (search for optimal projection for each d)
- Problem (2): robust ID estimates only if  $\mathcal{L}(\Pi^d)$  has large gap as a function of d if no gap, the estimation can be rather arbitrary

### Example: companies balance sheets

- consider D=38 balance sheet variables for N=8000 companies
- We find four manifolds with dimensions d=5.4,d=6.4,d=7.0, d=9.1
- Consider the financial risk of the companies assigned to different manifolds



Companies with higher risk are preferentially assigned to low dimensional manifolds!

### ID estimation: projective approach

- Example: Principal Component Analysis (PCA)
- Prjoects data onto linear subspace spanned by first *d* eigenvalues of

covariance matrix  $X^T X$ .

LOSS: 
$$\mathcal{L}(\Pi^d) = ||\sum_i \mathbf{x}_i \mathbf{x}_i^T - \mathbf{y}_i \mathbf{y}_i^T||$$





• How can one select an appropriate d?

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# ID estimation: TWO-NN

E Facco, M D'Errico, A Rodriguez, A Laio, Scientific Reports 7, 12140. (2017)

- points are sampled independently
- ρ constant over region A
- n=# of points in a region A
- n follows Poisson law  $P(n)=(\rho V)^n/n! \exp(-\rho V)$
- Consider hypersheprical shells defined by first and second neighbor of a point
- $f(v_{i1}, v_{i2}) = exp(-\rho v_{i2}) dv_{i1} dv_{i2}$
- derive  $f(r_{i1}, r_{i2})$
- derive  $f(r_{i2}/r_{i1})$



### Is the ID uniform?



Sometimes the model fails...

- 1) the density is strongly varying even on the scale of the first two neighbors
- 2) the dimension is not uniform in the dataset